




Systematic Review

Autonomous Vehicles in the Traffic Ecosystem: A Comprehensive Review of Integration, Impacts, and Policy Implications

Eugen Valentin Butilă ¹, Gheorghe-Daniel Voinea ^{1,*}, Răzvan Gabriel Boboc ¹ and Grigore Ambrosi ²

¹ Department of Automotive and Transport Engineering, Transilvania University of Brasov, 500036 Brasov, Romania; butila@unitbv.ro (E.V.B.); razvan.boboc@unitbv.ro (R.G.B.)

² Department of Transportation, Technical University of Moldova, MD-2004 Chisinau, Moldova; grigore.ambrosi@tran.utm.md

* Correspondence: daniel.voinea@unitbv.ro

Abstract

Autonomous vehicles (AVs) are expected to significantly influence road safety, traffic efficiency, and urban mobility. However, their real-world impacts depend not only on vehicle-level automation but also on interactions within the broader traffic ecosystem, including human-driven vehicles, vulnerable road users, infrastructure, and governance frameworks. This review provides a system-level synthesis of recent research on the integration of autonomous and connected autonomous vehicles in mixed traffic environments. Following PRISMA 2020 guidelines, 51 peer-reviewed studies published between 2016 and 2025 were systematically reviewed and thematically analyzed. The review addresses technological foundations, safety impacts, traffic flow and network performance, mixed traffic dynamics, infrastructure and urban systems, and policy and governance challenges. The findings indicate that AV impacts are highly non-linear and sensitive to market penetration rates, control strategies, and human behavioral adaptation. While high levels of automation and connectivity can improve safety, capacity, and traffic stability, early-stage deployment may temporarily increase delays and traffic conflicts. Policy measures—such as pricing, shared mobility integration, and regulatory oversight—are therefore critical to ensuring that AV deployment delivers sustainable and equitable mobility outcomes.

Keywords: connected autonomous vehicles; mixed traffic; urban mobility; intelligent transportation systems; transportation policy



Academic Editors: Nicolae
Vlad Burnete, Florin Mariasiu and
Calin Iclodean

Received: 19 January 2026
Revised: 15 February 2026
Accepted: 16 February 2026
Published: 19 February 2026

Copyright: © 2026 by the authors.
Licensee MDPI, Basel, Switzerland.
This article is an open access article
distributed under the terms and
conditions of the [Creative Commons
Attribution \(CC BY\) license](https://creativecommons.org/licenses/by/4.0/).

References

1. Salvini, P.; Kunze, L.; Jirotko, M. On self-driving cars and its (broken?) promises. A case study analysis of the German Act on Autonomous Driving. *Technol. Soc.* **2024**, *78*, 102628. [[CrossRef](#)]
2. Garikapati, D.; Shetiya, S.S. Autonomous Vehicles: Evolution of Artificial Intelligence and the Current Industry Landscape. *Big Data Cogn. Comput.* **2024**, *8*, 42. [[CrossRef](#)]
3. Zhang, Y.; Carballo, A.; Yang, H.; Takeda, K. Perception and sensing for autonomous vehicles under adverse weather conditions: A survey. *ISPRS J. Photogramm. Remote Sens.* **2023**, *196*, 146–177. [[CrossRef](#)]
4. SAE_International. *Taxonomy and Definitions for Terms Related to Driving Automation Systems for On-Road Motor Vehicles*; SAE_International: Warrendale, PA, USA, 2021.
5. König, A.L.; Boßow-Thies, S.; Krol, B. Female mobility—An empirical analysis of factors influencing women’s acceptance of Robo-Taxis using PLS-SEM. *Transp. Res. Part F Traffic Psychol. Behav.* **2025**, *114*, 933–952. [[CrossRef](#)]
6. Anund, A.; Ludovic, R.; Caroleo, B.; Hardestam, H.; Dahlman, A.; Skogsmo, I.; Nicaise, M.; Arnone, M. Lessons learned from setting up a demonstration site with autonomous shuttle operation—based on experience from three cities in Europe. *J. Urban Mobil.* **2022**, *2*, 100021. [[CrossRef](#)]
7. Xu, Z.; Zheng, N. Integrating connected autonomous shuttle buses as an alternative for public transport—A simulation-based study. *Multimodal Transp.* **2024**, *3*, 100133. [[CrossRef](#)]
8. Singh, S. *Critical Reasons for Crashes Investigated in the National Motor Vehicle Crash Causation Survey*; U.S. Department of Transportation: Washington DC, USA, 2015.
9. Abdelghaffar, H.M.; Menéndez, M. Influential Control Parameters for Autonomous Vehicles in a Mixed Environment. *IEEE Open J. Veh. Technol.* **2024**, *5*, 927–939. [[CrossRef](#)]
10. Aittoniemi, E. Evidence on impacts of automated vehicles on traffic flow efficiency and emissions: Systematic review. *IET Intell. Transp. Syst.* **2022**, *16*, 1306–1327. [[CrossRef](#)]
11. Stueger, P.N.; Niels, T.; Margreiter, M.; Bogenberger, K. Impact of Connected and Automated Vehicles on Metropolitan Road Traffic: Test Site Munich, Germany. *Transp. Res. Rec.* **2025**, *2679*, 309–323. [[CrossRef](#)]
12. He, Y.; Xiang, D.; Wang, D. Traffic safety evaluation of emerging mixed traffic flow at freeway merging area considering driving behavior. *Sci. Rep.* **2025**, *15*, 10686. [[CrossRef](#)]
13. Debbaghi, F.-Z.; Rombaut, E.; Vanhaverbeke, L. Lessons learned from shared automated vehicles pilots in Europe: An evaluation of safety, traffic, and user acceptance. *Case Stud. Transp. Policy* **2025**, *20*, 101447. [[CrossRef](#)]
14. Wang, J.; Pant, Y.V.; Jiang, Z. Learning-based modeling of human-autonomous vehicle interaction for improved safety in mixed-vehicle platooning control. *Transp. Res. Part C Emerg. Technol.* **2024**, *162*, 104600. [[CrossRef](#)]
15. Shetty, A.; Yu, M.; Kurzhanskiy, A.; Grembek, O.; Tavafoghi, H.; Varaiya, P. Safety challenges for autonomous vehicles in the absence of connectivity. *Transp. Res. Part C Emerg. Technol.* **2021**, *128*, 103133. [[CrossRef](#)]
16. Liu, C.; Zyryanov, V.; Topilin, I.; Feofilova, A.; Shao, M. Investigating the Impacts of Autonomous Vehicles on the Efficiency of Road Network and Traffic Demand: A Case Study of Qingdao, China. *Sensors* **2024**, *24*, 5110. [[CrossRef](#)] [[PubMed](#)]
17. Emory, K.; Douma, F.; Cao, J. Autonomous vehicle policies with equity implications: Patterns and gaps. *Transp. Res. Interdiscip. Perspect.* **2022**, *13*, 100521. [[CrossRef](#)]
18. Chang, Q.; Chen, H. Impacts of autonomous vehicles on freeway with conditional isolated and dedicated lanes. *Sci. Rep.* **2025**, *15*, 21374. [[CrossRef](#)]
19. Fujiu, M.; Morisaki, Y.; Takayama, J. Impact of Autonomous Vehicles on Traffic Flow in Rural and Urban Areas Using a Traffic Flow Simulator. *Sustainability* **2024**, *16*, 658. [[CrossRef](#)]

20. Lu, Q.; Tettamanti, T.; Hörcher, D.; Varga, I. The impact of autonomous vehicles on urban traffic network capacity: An experimental analysis by microscopic traffic simulation. *Transp. Lett.* **2020**, *12*, 540–549. [[CrossRef](#)]
21. Fagnant, D.J.; Kockelman, K. Preparing a nation for autonomous vehicles: Opportunities, barriers and policy recommendations. *Transp. Res. Part A Policy Pract.* **2015**, *77*, 167–181. [[CrossRef](#)]
22. Wadud, Z.; MacKenzie, D.; Leiby, P. Help or hindrance? The travel, energy and carbon impacts of highly automated vehicles. *Transp. Res. Part A Policy Pract.* **2016**, *86*, 1–18. [[CrossRef](#)]
23. Narayanan, S.; Chaniotakis, E.; Antoniou, C. Shared autonomous vehicle services: A comprehensive review. *Transp. Res. Part C Emerg. Technol.* **2020**, *111*, 255–293. [[CrossRef](#)]
24. Luca, O.; Andrei, L.; Iacoboaia, C.; Gaman, F. Unveiling the Hidden Effects of Automated Vehicles on “Do No Significant Harm” Components. *Sustainability* **2023**, *15*, 11265. [[CrossRef](#)]
25. Shladover, S.E. Connected and automated vehicle systems: Introduction and overview. *J. Intell. Transp. Syst.* **2018**, *22*, 190–200. [[CrossRef](#)]
26. Greifenstein, M.; Nordhoff, S.; Wang, X.; Atluri, B. Riding into the future: What drives the use of robotaxis in San Francisco? *Transp. Res. Part A Policy Pract.* **2026**, *203*, 104763. [[CrossRef](#)]
27. Badue, C.; Guidolini, R.; Carneiro, R.V.; Azevedo, P.; Cardoso, V.B.; Forechi, A.; Jesus, L.; Berriel, R.; Paixão, T.M.; Mutz, F.; et al. Self-driving cars: A survey. *Expert Syst. Appl.* **2021**, *165*, 113816. [[CrossRef](#)]
28. Lee, E.H.; Lee, E. Congestion boundary approach for phase transitions in traffic flow. *Transp. B Transp. Dyn.* **2024**, *12*, 2379377. [[CrossRef](#)]
29. Peng, G.; Wu, K.; Jiao, W.; Yang, S.; Wu, Z.; Xu, L.; Lu, C.; Tan, H.; Xia, D. Congestion transition in a heterogeneous ring road car-following model incorporating visual angle defect and speed limit effects. *Chaos Solitons Fractals* **2026**, *204*, 117710. [[CrossRef](#)]
30. Pan, Y.; Cheng, Q.; Li, A.; Zhang, J.; Guo, J.; Chen, Y. Analysis of congestion key parameters, dynamic discharge process, and capacity estimation at urban freeway bottlenecks: A case study in Beijing, China. *Transp. Lett.* **2025**, *17*, 984–1003. [[CrossRef](#)]
31. Paden, B.; Čáp, M.; Yong, S.Z.; Yershov, D.; Frazzoli, E. A Survey of Motion Planning and Control Techniques for Self-Driving Urban Vehicles. *IEEE Trans. Intell. Veh.* **2016**, *1*, 33–55. [[CrossRef](#)]
32. Aksjonov, A.; Kyrki, V. Rule-Based Decision-Making System for Autonomous Vehicles at Intersections with Mixed Traffic Environment. In Proceedings of the 2021 IEEE International Intelligent Transportation Systems Conference (ITSC), Indianapolis, IN, USA, 19–22 September 2021; pp. 660–666.
33. Talebpour, A.; Mahmassani, H.S. Influence of connected and autonomous vehicles on traffic flow stability and throughput. *Transp. Res. Part C Emerg. Technol.* **2016**, *71*, 143–163. [[CrossRef](#)]
34. Campolo, C.; Molinaro, A.; Scopigno, R. From today’s VANETs to tomorrow’s planning and the bets for the day after. *Veh. Commun.* **2015**, *2*, 158–171. [[CrossRef](#)]
35. Wang, H.; Shao, W.; Sun, C.; Yang, K.; Cao, D.; Li, J. A Survey on an Emerging Safety Challenge for Autonomous Vehicles: Safety of the Intended Functionality. *Engineering* **2024**, *33*, 17–34. [[CrossRef](#)]
36. OECD; ITF. *Preparing Infrastructure for Automated Vehicles*; OECD: Paris, France, 2023.
37. Page, M.J.; McKenzie, J.E.; Bossuyt, P.M.; Boutron, I.; Hoffmann, T.C.; Mulrow, C.D.; Shamseer, L.; Tetzlaff, J.M.; Akl, E.A.; Brennan, S.E.; et al. The PRISMA 2020 statement: An updated guideline for reporting systematic reviews. *BMJ* **2021**, *372*, n71. [[CrossRef](#)] [[PubMed](#)]
38. Huang, Y.; Ye, Y.J.; Sun, J.; Tian, Y. Characterizing the Impact of Autonomous Vehicles on Macroscopic Fundamental Diagrams. *IEEE Trans. Intell. Transp. Syst.* **2023**, *24*, 6530–6541. [[CrossRef](#)]
39. Li, G.; Jiao, Y.; Calvert, S.C.; Van Lint, J.W.C.H. Lateral conflict resolution data derived from Argoverse-2: Analysing safety and efficiency impacts of autonomous vehicles at intersections. *Transp. Res. Part C Emerg. Technol.* **2024**, *167*, 104802. [[CrossRef](#)]
40. Almusawi, A.; Albdairi, M.; Qadri, S. Integrating Autonomous Vehicles (AVs) into Urban Traffic: Simulating Driving and Signal Control. *Appl. Sci.* **2024**, *14*, 8851. [[CrossRef](#)]
41. Sadid, H.; Antoniou, C. A simulation-based impact assessment of autonomous vehicles in urban networks. *IET Intell. Transp. Syst.* **2024**, *18*, 1677–1696. [[CrossRef](#)]
42. Gelauff, G.; Ossokina, I.; Teulings, C. Spatial and welfare effects of automated driving: Will cities grow, decline or both? *Transp. Res. Part A Policy Pract.* **2019**, *121*, 277–294. [[CrossRef](#)]
43. Liu, C.; Chen, K.; Bao, Z.; Ng, S.T.; Zhang, C.; Jiang, Z. Assessing the impacts of connected-and-autonomous vehicle management strategy on the environmental sustainability of urban expressway system. *Sustain. Cities Soc.* **2023**, *99*, 104904. [[CrossRef](#)]
44. Zhang, J.; Bai, Y.Z.; He, J.; Wang, T. On the impacts of dedicated lanes for CAVs in mixed traffic: Evaluation using a modified cell transmission model. *Phys. A Stat. Mech. Its Appl.* **2025**, *662*, 130418. [[CrossRef](#)]
45. Park, J.; Jang, S.; Ko, J.H. Effects of Exclusive Lanes for Autonomous Vehicles on Urban Expressways under Mixed Traffic of Autonomous and Human-Driven Vehicles. *Sustainability* **2024**, *16*, 26. [[CrossRef](#)]

46. Majstorovic, Ä.; Tisljaric, L.; Ivanjko, E.; Caric, T. Urban Traffic Signal Control under Mixed Traffic Flows: Literature Review. *Appl. Sci.* **2023**, *13*, 4484. [[CrossRef](#)]
47. Papadoulis, A.; Imprialou, M.; Feng, Y.; Quddus, M. Simulating and Modelling the Safety Impact of Connected and Autonomous Vehicles in Mixed Traffic: Platoon Size, Sensor Error, and Path Choice. *Machines* **2024**, *12*, 371. [[CrossRef](#)]
48. Guan, H.; Chen, X.; Meng, Q. Jam propagation in mixed traffic of autonomous and human-driven vehicles: A random walk-based analysis. *Transp. Res. Part C Emerg. Technol.* **2025**, *180*, 105310. [[CrossRef](#)]
49. Mahmassani, H.S. Autonomous Vehicles and Connected Vehicle Systems: Flow and Operations Considerations. *Transp. Sci.* **2016**, *50*, 1140–1162. [[CrossRef](#)]
50. Pham, M.; Xiong, K. A survey on security attacks and defense techniques for connected and autonomous vehicles. *Comput. Secur.* **2021**, *109*, 102269. [[CrossRef](#)]
51. Andreotti, E.; Selpi; Boyraz, P. Potential impact of autonomous vehicles in mixed traffic from simulation using real traffic flow. *J. Intell. Connect. Veh.* **2023**, *6*, 1–15. [[CrossRef](#)]
52. Chu, K.F.; Fan, C.; Iida, F. Navigating Mixed Traffic: Current State and Future Challenges in Integrating Autonomous and Human-Driven Vehicles. In *Proceedings of the Proceedings of IEEE Workshop on Advanced Robotics and its Social Impacts; ARSO: Nairobi, Kenya, 2024*; pp. 241–246.
53. Wang, J.; Zhou, L.; Yang, C. Decision model based on driving-mode misidentification for mixed AV–HDV straight–left conflict interactions at two-phase signalized intersections. *Phys. A Stat. Mech. Its Appl.* **2025**, *677*, 130943. [[CrossRef](#)]
54. Louati, A.; Louati, H.; Kariri, E.; Neifar, W.; Hassan, M.K.; Khairi, M.H.H.; Farahat, M.A.; El-Hoseny, H.M. Sustainable Smart Cities through Multi-Agent Reinforcement Learning-Based Cooperative Autonomous Vehicles. *Sustainability* **2024**, *16*, 1779. [[CrossRef](#)]
55. Hayward, J.C. Near-miss determination through use of a scale of danger. *Highw. Res. Rec.* **1972**, *384*, 24–34.
56. Gettman, D.; Head, L. Surrogate Safety Measures from Traffic Simulation Models. *Transp. Res. Rec.* **2003**, *1840*, 104–115. [[CrossRef](#)]
57. Wang, Z.; Zhao, X.M.; Xu, Z.G.; Li, X.P.; Qu, X.B. Modeling and field experiments on autonomous vehicle lane changing with surrounding human-driven vehicles. *Comput.-AIDED Civ. Infrastruct. Eng.* **2021**, *36*, 877–889. [[CrossRef](#)]
58. Li, Y.; Wang, L.; Xuan, Z.; Shen, W. Game-theory based truck platoon avoidance modes selection near the highway off-ramp in mixed traffic environment. *Front. Phys.* **2024**, *12*, 1371233. [[CrossRef](#)]
59. Wang, Y.; Jiang, Y.; Wu, Y.; Yao, Z. Mitigating traffic oscillation through control of connected automated vehicles: A cellular automata simulation. *Expert Syst. Appl.* **2024**, *235*, 121275. [[CrossRef](#)]
60. Zhang, F.; Lu, J.; Hu, X. Traffic Equilibrium for Mixed Traffic Flows of Human-Driven Vehicles and Connected and Autonomous Vehicles in Transportation Networks under Tradable Credit Scheme. *J. Adv. Transp.* **2020**, *2020*, 8498561. [[CrossRef](#)]
61. Talebpour, A.; Mahmassani, H.S.; Bustamante, F.E. Modeling Driver Behavior in a Connected Environment: Integrated Microscopic Simulation of Traffic and Mobile Wireless Telecommunication Systems. *Transp. Res. Rec.* **2016**, *2560*, 75–86. [[CrossRef](#)]
62. Peng, G.; Wang, W.; Tan, H. Phase transitions in a heterogeneous lattice hydrodynamic model involving both communication distance and memory time duration differences. *Chaos Solitons Fractals* **2024**, *188*, 115502. [[CrossRef](#)]
63. Liu, Y.; Guo, J.; Taplin, J.; Wang, Y. Characteristic analysis of mixed traffic flow of regular and autonomous vehicles using cellular automata. *J. Adv. Transp.* **2017**, *2017*, 8142074. [[CrossRef](#)] [[PubMed](#)]
64. Kouvelas, A.; Perrin, J.P.; Fokri, S.; Geroliminis, N. Exploring the impact of autonomous vehicles in urban networks and potential new capabilities for perimeter control. In *Proceedings of the 2017 5th IEEE International Conference on Models and Technologies for Intelligent Transportation Systems (MT-ITS); IEEE: Piscataway, NJ, USA, 2017*; pp. 19–24.
65. Jo, Y.; Kim, J.; Oh, C.; Kim, I.; Lee, G. Benefits of travel time savings by truck platooning in Korean freeway networks. *Transp. Policy* **2019**, *83*, 37–45. [[CrossRef](#)]
66. Liu, C.; Zhang, C.; Yu, C.; Chen, K.; Jiang, Z. Joint Optimization of Longitudinal and Lateral Locations of Autonomous-Vehicle-Dedicated Lanes on Expressways. *IEEE Trans. Intell. Transp. Syst.* **2024**, *25*, 430–442. [[CrossRef](#)]
67. Zhang, X.; Zhang, H.; Yan, S.; Xie, M.; Wang, Y. Parking pricing strategies in the era of autonomous vehicles. *Transp. Policy* **2025**, *166*, 87–100. [[CrossRef](#)]
68. Liu, Z.; Li, R.; Dai, J. Effects and feasibility of shared mobility with shared autonomous vehicles: An investigation based on data-driven modeling approach. *Transp. Res. Part A Policy Pract.* **2022**, *156*, 206–226. [[CrossRef](#)]
69. Mo, D.; Chen, X.; Zhang, J. Modeling and Managing Mixed On-Demand Ride Services of Human-Driven Vehicles and Autonomous Vehicles. *Transp. Res. Part B Methodol.* **2022**, *157*, 80–119. [[CrossRef](#)]
70. Liu, A.; Zhong, S.; Sun, D.; Gong, Y.; Fan, M.; Song, Y. Joint optimal pricing strategy of shared autonomous vehicles and road congestion pricing: A regional accessibility perspective. *Cities* **2024**, *146*, 104742. [[CrossRef](#)]
71. Li, S.; Tavafoghi, H.; Poolla, K.; Varaiya, P. Regulating TNCs: Should Uber and Lyft set their own rules? *Transp. Res. Part B Methodol.* **2019**, *129*, 193–225. [[CrossRef](#)]
72. Ao, D.; Gao, J.; Lai, Z.; Li, S. Regulating transportation network companies with a mixture of autonomous vehicles and for-hire human drivers. *Transp. Res. Part A Policy Pract.* **2024**, *180*, 103975. [[CrossRef](#)]

73. Jia, D.; Sun, J.; Sharma, A.; Zheng, Z.; Liu, B. Integrated simulation platform for conventional, connected and automated driving: A design from cyber–physical systems perspective. *Transp. Res. Part C Emerg. Technol.* **2021**, *124*, 102984. [[CrossRef](#)]
74. Liu, P.F.; Fan, W.D. Exploring the impact of connected and autonomous vehicles on mobility and environment at signalized intersections through vehicle-to-infrastructure (V2I) and infrastructure-to-vehicle (I2V) communications. *Transp. Plan. Technol.* **2021**, *44*, 129–138. [[CrossRef](#)]
75. Xu, Z.; Jiang, T.; Zheng, N. Developing and analyzing eco-driving strategies for on-road emission reduction in urban transport systems—A VR-enabled digital-twin approach. *Chemosphere* **2022**, *305*, 135372. [[CrossRef](#)]
76. Santana, E.F.Z.; Covas, G.; Duarte, F.; Santi, P.; Ratti, C.; Kon, F. Transitioning to a driverless city: Evaluating a hybrid system for autonomous and non-autonomous vehicles. *Simul. Model. Pract. Theory* **2021**, *107*, 102210. [[CrossRef](#)]
77. Guo, Y.; Souders, D.; Labi, S.; Peeta, S.; Benedyk, I.; Li, Y. Paving the way for autonomous Vehicles: Understanding autonomous vehicle adoption and vehicle fuel choice under user heterogeneity. *Transp. Res. Part A Policy Pract.* **2021**, *154*, 364–398. [[CrossRef](#)]
78. Zhang, L.; Lu, Y.; Chen, N.; Wang, P.; Kong, W.; Wang, Q.; Qin, G.; Mou, Z. Optimization of Roadside Unit Deployment on Highways under the Evolution of Intelligent Connected-Vehicle Permeability. *Sustainability* **2023**, *15*, 11112. [[CrossRef](#)]
79. Ye, S.; Li, T.; Li, R.; Zhang, Z.; Lv, P.; Pan, Z. Impact of HDMap-based Dynamic Dedicated Lanes for CAVs in Urban Networks. In Proceedings of the 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), 24–28 September 2023; pp. 2363–2369.
80. Chen, X.D.; Zhang, F.; Guan, H.; Meng, Q. Two-dimensional lane configuration design approach for Autonomous Vehicle Dedicated Lanes in urban networks. *Transp. Res. PART E-Logist. Transp. Rev.* **2025**, *194*, 103938. [[CrossRef](#)]
81. Hawkins, J.; Nurul Habib, K. Integrated models of land use and transportation for the autonomous vehicle revolution. *Transp. Rev.* **2019**, *39*, 66–83. [[CrossRef](#)]
82. Alatawneh, A.; Torok, A. Use-stage emissions of conventional, battery electric, and autonomous vehicles in Europe. *Case Stud. Transp. Policy* **2025**, *20*, 101398. [[CrossRef](#)]
83. Guan, H.; Wang, H.; Meng, Q.; Mak, C.L. Markov chain-based traffic analysis on platooning effect among mixed semi- and fully-autonomous vehicles in a freeway lane. *Transp. Res. Part B Methodol.* **2023**, *173*, 176–202. [[CrossRef](#)]
84. Metz, D. Developing Policy for Urban Autonomous Vehicles: Impact on Congestion. *Urban Sci.* **2018**, *2*, 33. [[CrossRef](#)]
85. Mo, L.; Cui, Z.; Jia, R.; Dong, K.; Zhao, C. How does autonomous vehicles affect taxi industry? A two-stage Van Damme based tripartite evolutionary game perspective. *Res. Transp. Econ.* **2024**, *103*, 101387. [[CrossRef](#)]
86. Torabi, K.F.; Araghi, Y.; van Oort, N.; Hoogendoorn, S. Passengers preferences for using emerging modes as first/last mile transport to and from a multimodal hub case study Delft Campus railway station. *Case Stud. Transp. Policy* **2022**, *10*, 300–314. [[CrossRef](#)]

Disclaimer/Publisher’s Note: The statements, opinions and data contained in all publications are solely those of the individual author(s) and contributor(s) and not of MDPI and/or the editor(s). MDPI and/or the editor(s) disclaim responsibility for any injury to people or property resulting from any ideas, methods, instructions or products referred to in the content.